

Eady's Model

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PO Theory Seminar
SIO, Fall 2014

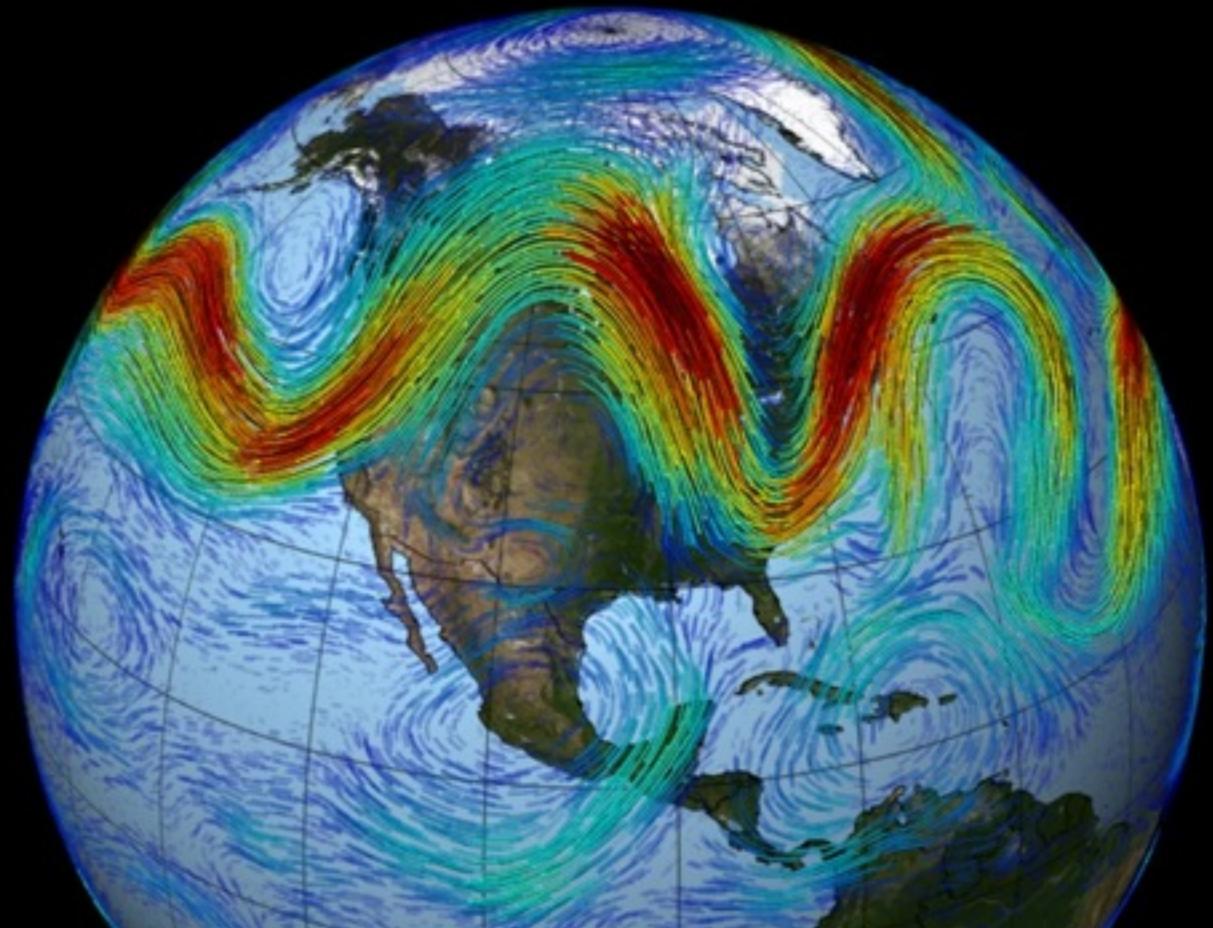


Image Courtesy NASA

Main References

1. Pedlosky, 1987: GFD, 2nd ed., Chapter 7.
2. Vallis, 2006: AOFD, Chapter 6.
3. Eady, 1949: Long Waves and Cyclone Waves, *Tellus*, 1.

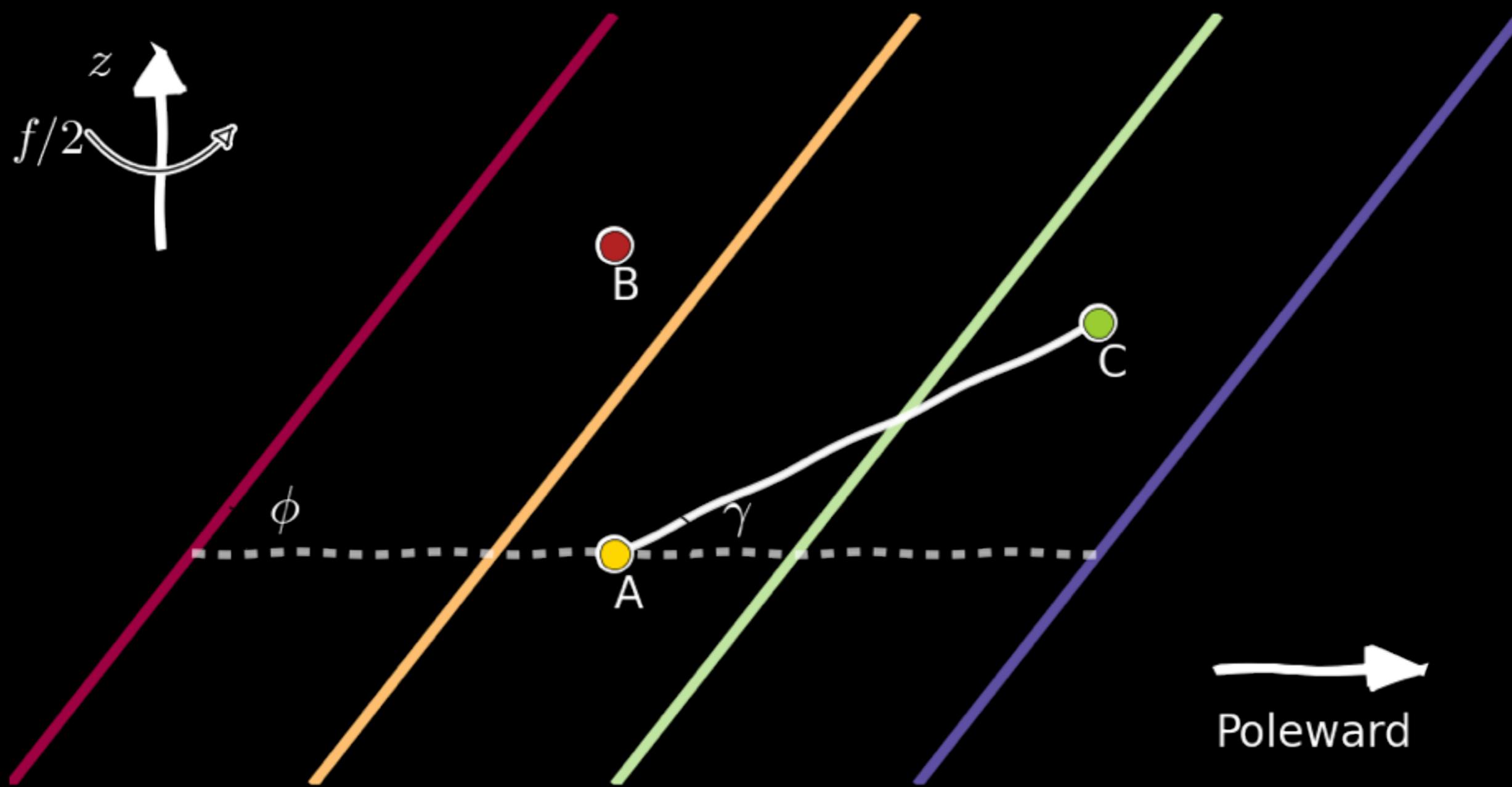
Eady's triumph

My Goal Today

Show the basic nature of baroclinic instability
of large-scale flows

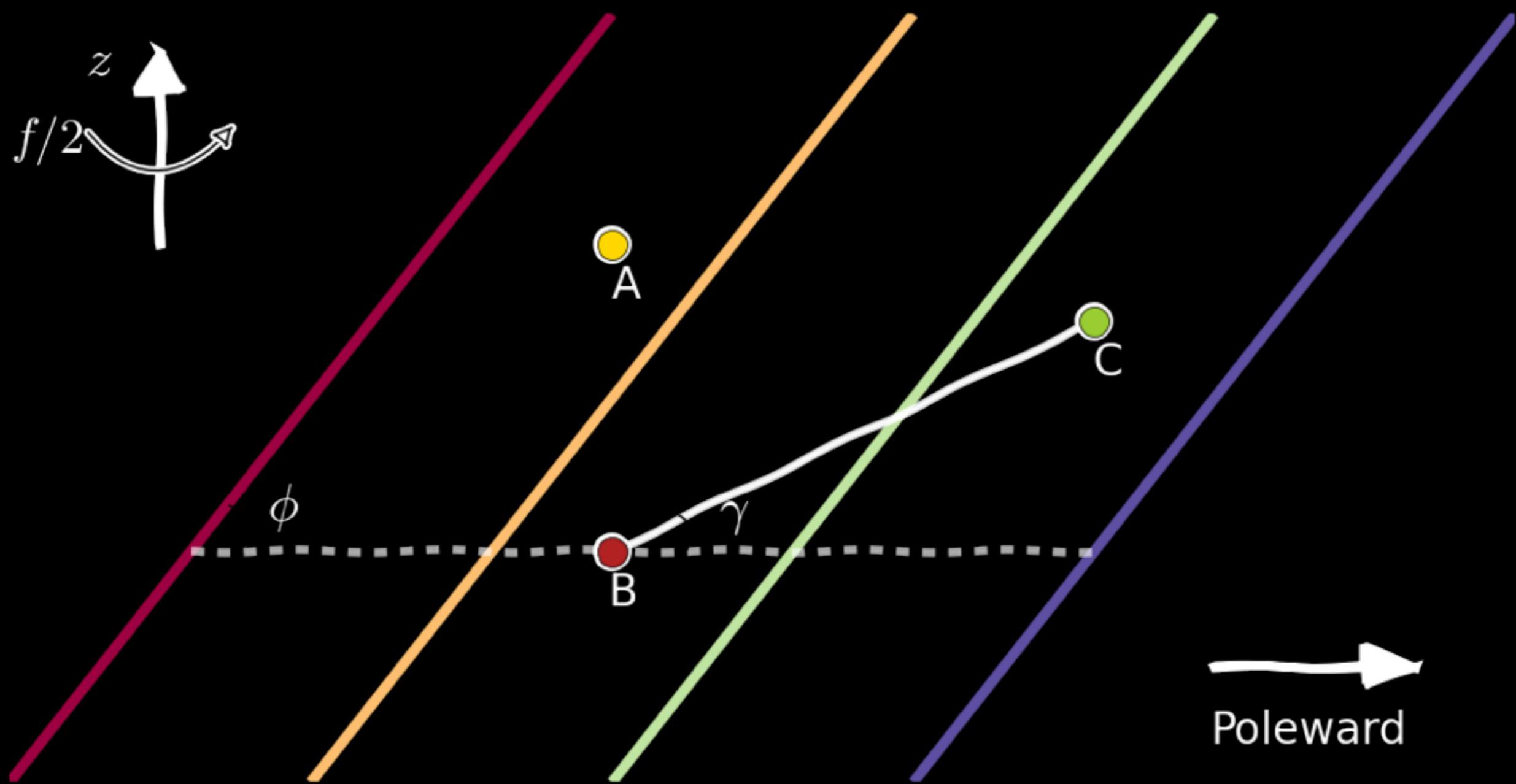
Elements of Baroclinic Instability

The Basic Mechanism



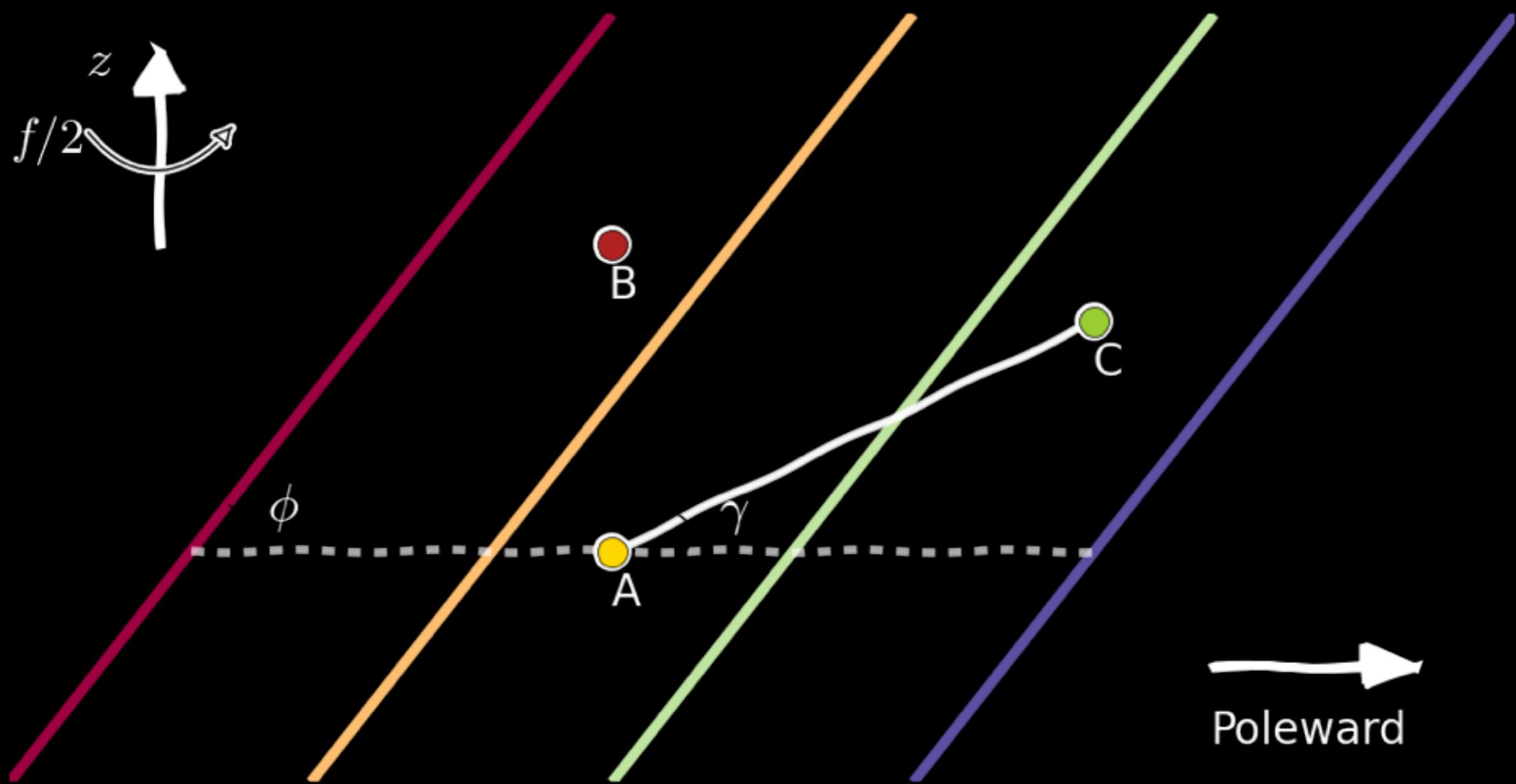
Pedlosky 1987; Vallis 2006

The Basic Mechanism



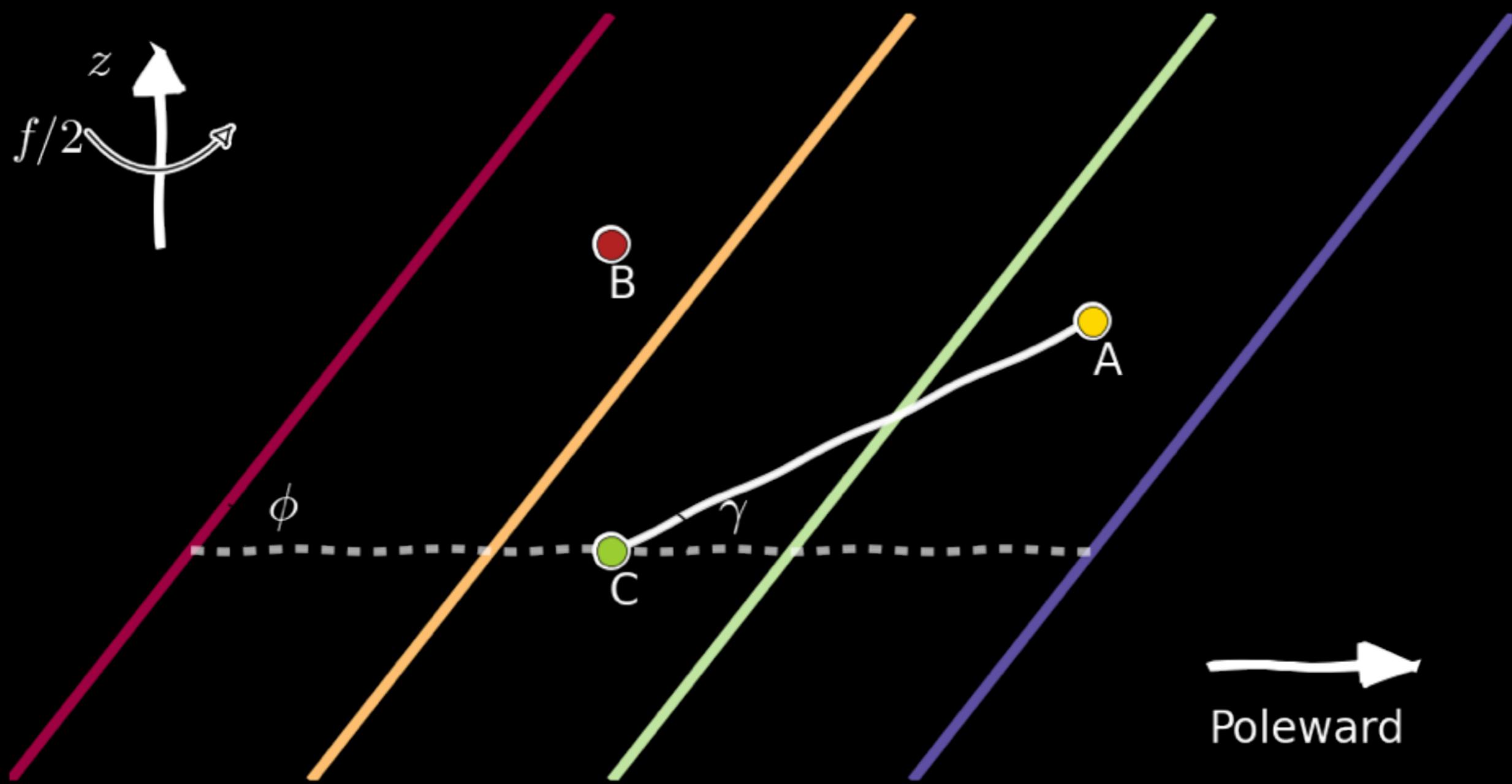
Pedlosky 1987; Vallis 2006

The Basic Mechanism



Pedlosky 1987; Vallis 2006

The Basic Mechanism



Pedlosky 1987; Vallis 2006

QG Equations

$$q_t + J(\psi, q) = 0, \quad 0 < z < H$$

$$b_t + J(\psi, b) = 0, \quad z = 0, H$$

$$q = \beta y + \nabla^2 \psi + \left[\frac{f_0^2}{N^2(z)} \psi_z \right]_z$$

$$b = f_0 \psi_z$$

Linear Stability Analysis

Linearization

Zonal mean flow

$$U(y, z) = -\Psi_y, \quad f_0 U_z = -B_y$$

Total flow = mean + eddy (infinitesimal)

$$\Psi(y, z) + \psi(x, y, z, t)$$

Linearization

$$q_t - \Psi_y q_x + \psi_x Q_y = 0, \quad 0 < z < H$$

$$b_t - \Psi_y b_x + \psi_x B_y = 0, \quad z = 0, H$$

$$q(x, y, z, t) = \nabla^2 \psi + \left[\frac{f_0^2}{N^2(z)} \psi_z \right]_z$$

$$Q(y, z) = \beta y + \nabla^2 \Psi \left[\frac{f_0^2}{N^2(z)} \Psi_z \right]_z$$

Normal Modes

$$\psi(x, y, z, t) = \operatorname{Re} \phi(y, z) \exp [ik(x - ct)]$$

$$(U - c) \left\{ \phi_{yy} + \left[\frac{f_0^2}{N^2(z)} \phi_z \right] - k^2 \phi \right\} + Q_y \phi = 0, \quad 0 < z < H$$

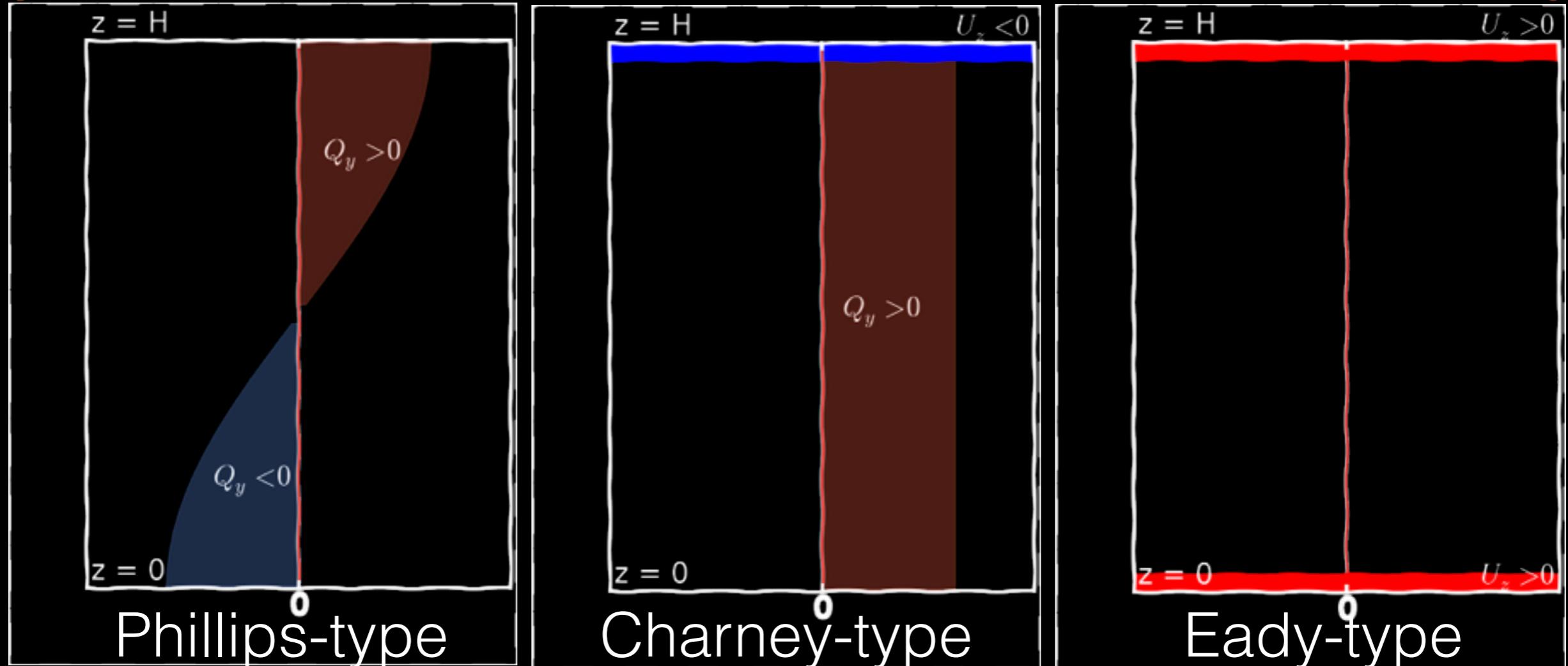
$$(U - c) \phi_z - U_z \phi = 0, \quad z = 0, H$$

Necessary Conditions

$$\int_0^{2L} dy \left\{ \int_0^H \frac{|\phi|^2}{|U - c|^2} Q_y dz + \frac{f_0^2}{N^2(z)} \frac{|\phi|^2}{|U - c|^2} U_z \Big|_0^H \right\} = 0$$

Necessary Conditions

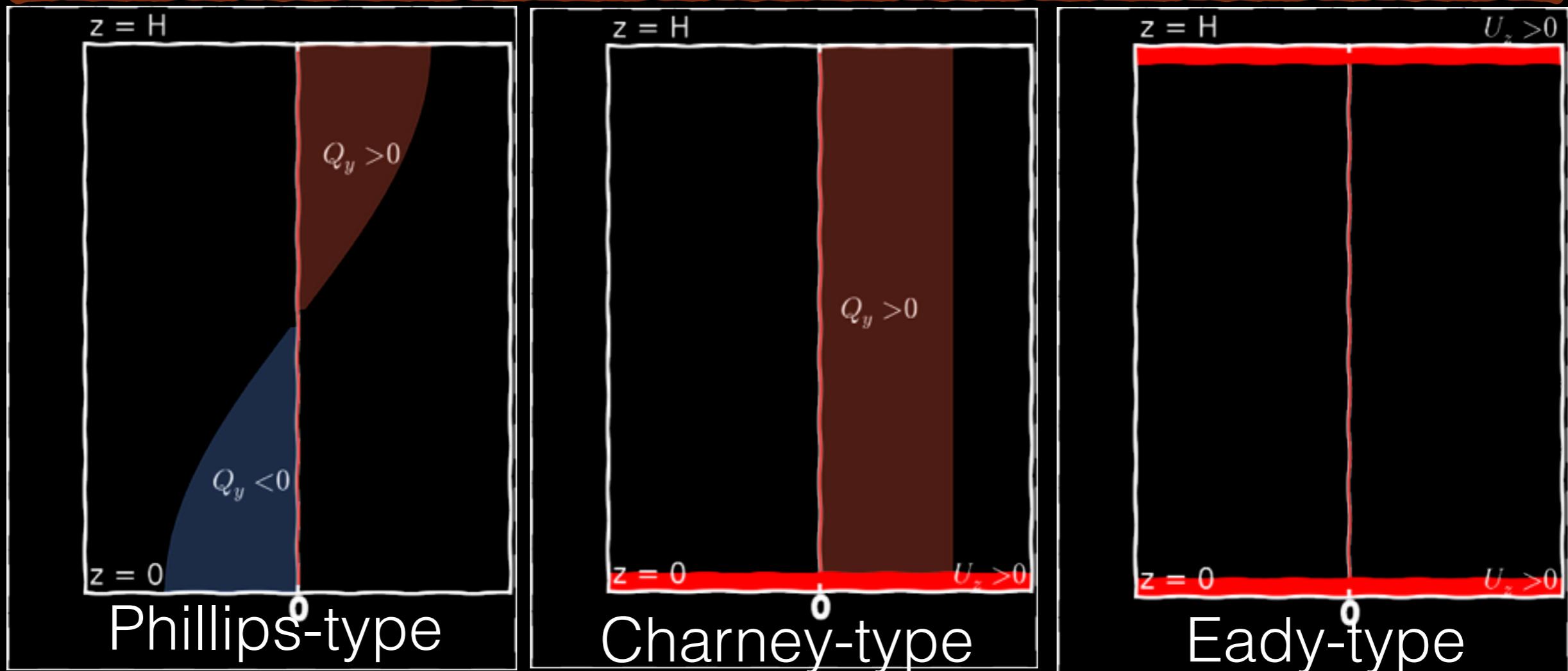
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Pedlosky 1987; Vallis 2006

Necessary Conditions

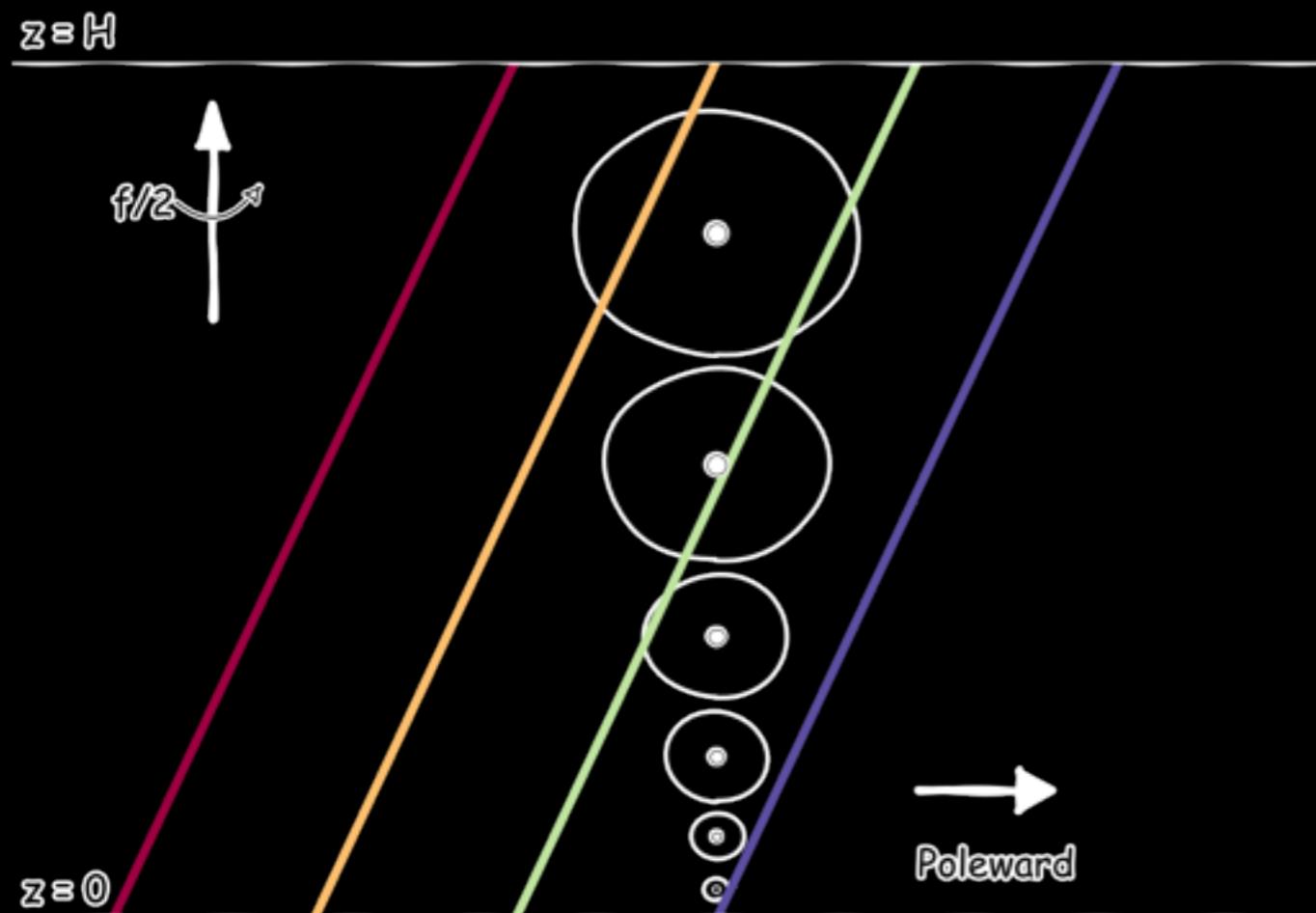
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Pedlosky 1987; Vallis 2006

Eady's Problem

Eady's Model: Set up



$$\left. \frac{\partial z}{\partial y} \right)_B = \frac{f_0 \Lambda}{N^2}$$

$$U(z) = \Lambda z$$
$$N^2 = \text{const.}$$
$$\beta = 0 \text{ (} f - \text{plane)} \text{}$$

$$Q = Q_y = 0$$

Normal Mode Equation

$$(U - c) \left\{ \phi_{yy} + \left[\frac{f_0^2}{N^2(z)} \phi_z \right] - k^2 \phi \right\} + Q_y \phi = 0, \quad 0 < z < H$$

$$(U - c) \phi_z - U_z \phi = 0, \quad z = 0, H$$

Normal Mode Equation

$$(U - c) \left\{ \phi_{yy} + \left[\frac{f_0^2}{N^2(z)} \phi_z \right] - k^2 \phi \right\} + \cancel{Q}_y \phi = 0, \quad 0 < z < H$$

$$(U - c) \phi_z - U_z \phi = 0, \quad z = 0, H$$

$Q_y = 0 \rightarrow$ NO critical layers !

Normal Mode Equation

$$(\Lambda z - c) \left[\phi_{yy} + \frac{f_0^2}{N^2} \phi_{zz} - k^2 \phi \right] = 0, \quad 0 < z < H$$

$$(\Lambda z - c) \phi_z - \Lambda \phi = 0, \quad z = 0, H$$

Perturbations confined in a channel of width $2L$

$$\phi(y, z) = \cos(l_n y) \varphi(z)$$

$$l_n = (2n + 1) \frac{\pi}{2L}, \quad n = 0, 1, 2, \dots$$

Normal Mode Equation

$$(\Lambda z - c) \left[\varphi_{zz} - \frac{\mu^2}{H^2} \varphi \right] = 0, \quad 0 < z < H$$

$$(\Lambda z - c)\varphi(z) - \Lambda\varphi = 0, \quad z = 0, H$$

$$\mu \stackrel{\text{def}}{=} \kappa L_d$$

$$\kappa^2 = k^2 + l_n^2,$$

$$L_d \stackrel{\text{def}}{=} \frac{NH}{f_0}$$

$$\varphi(z) = A \cosh \left(\mu \frac{z}{H} \right) + B \sinh \left(\mu \frac{z}{H} \right)$$

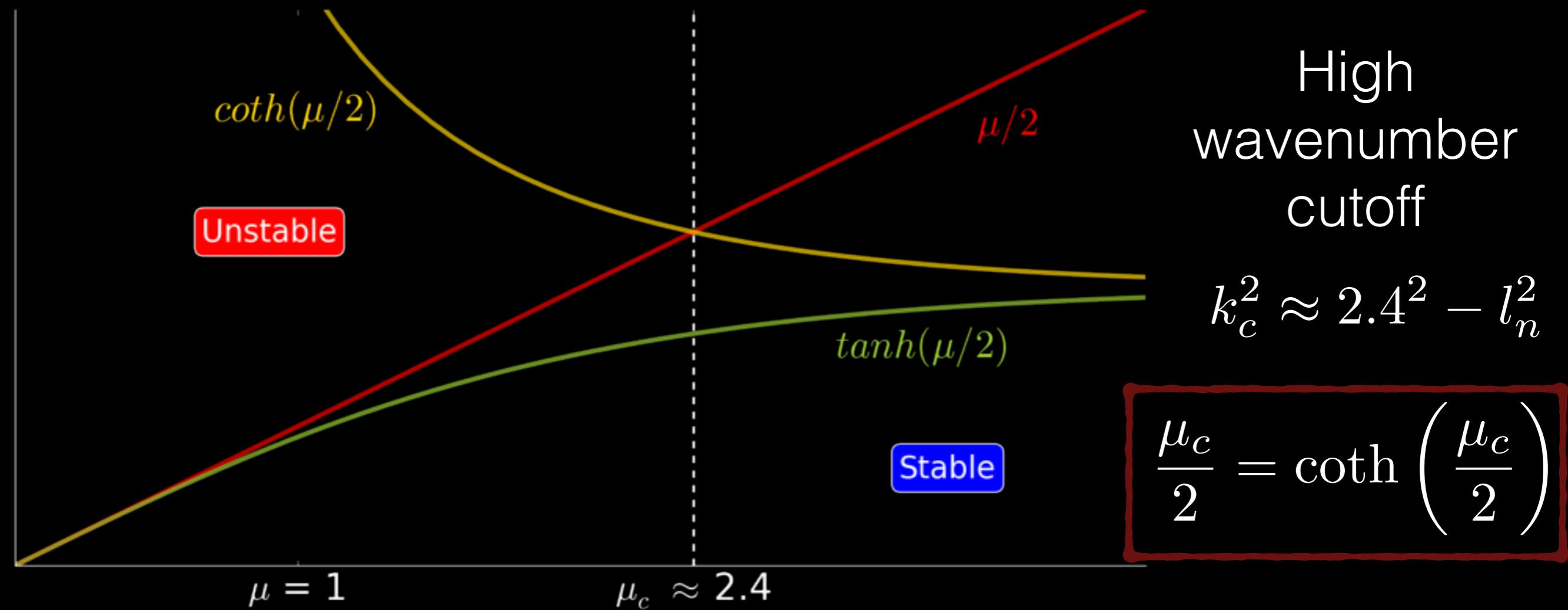
BCs determine
the physics

Eigenproblem Solution

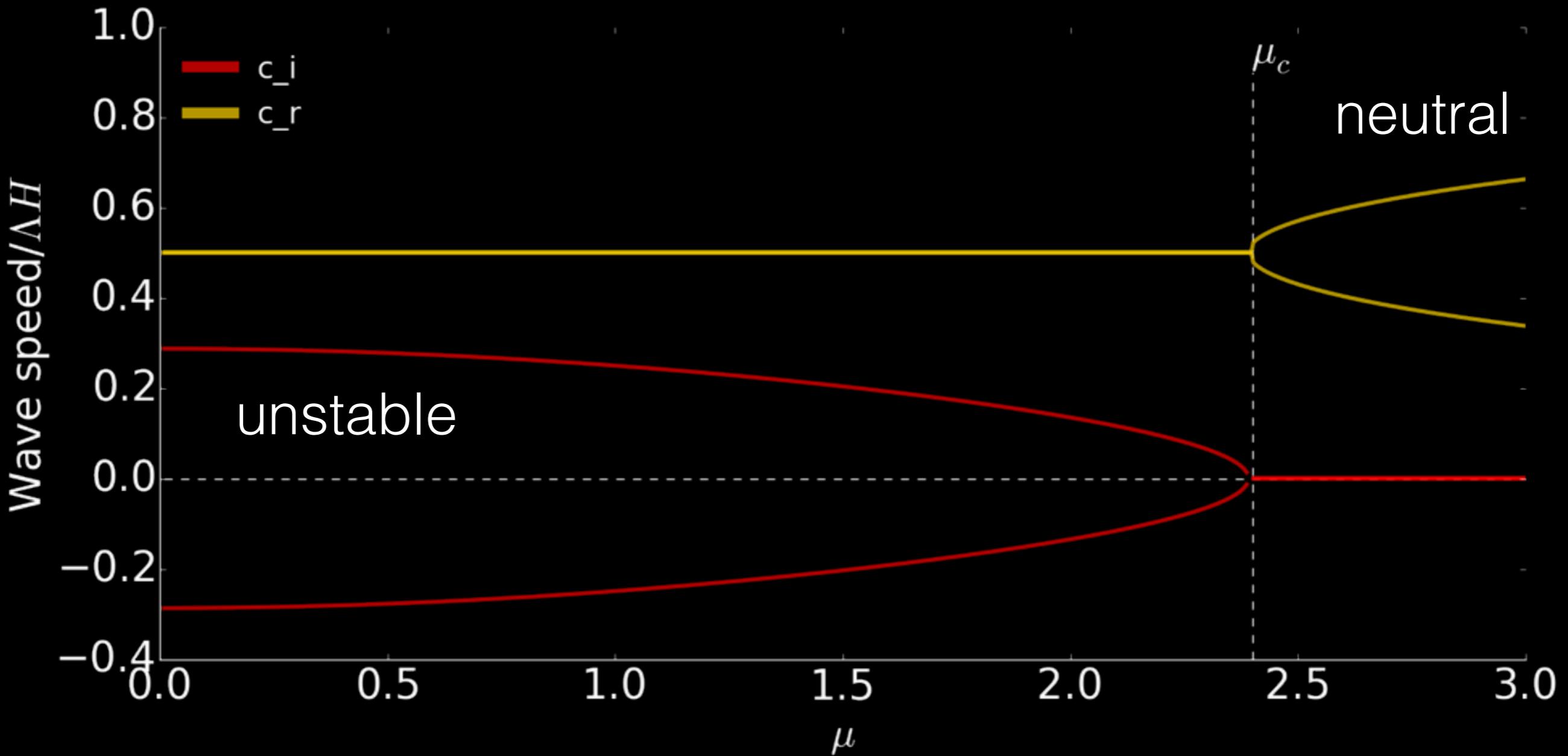
$$c = \frac{\Lambda H}{2} \pm \frac{\Lambda H}{\mu} \left\{ \left[\frac{\mu}{2} - \tanh \left(\frac{\mu}{2} \right) \right] \left[\frac{\mu}{2} - \coth \left(\frac{\mu}{2} \right) \right] \right\}^{1/2}$$

Eigenproblem Solution

$$c = \frac{\Lambda H}{2} \pm \frac{\Lambda H}{\mu} \left\{ \left[\frac{\mu}{2} - \tanh\left(\frac{\mu}{2}\right) \right] \left[\frac{\mu}{2} - \coth\left(\frac{\mu}{2}\right) \right] \right\}^{1/2}$$



Wave Speeds



Steering level at $z = H/2$ ($c_r = U$)

$$L/L_d = 8$$

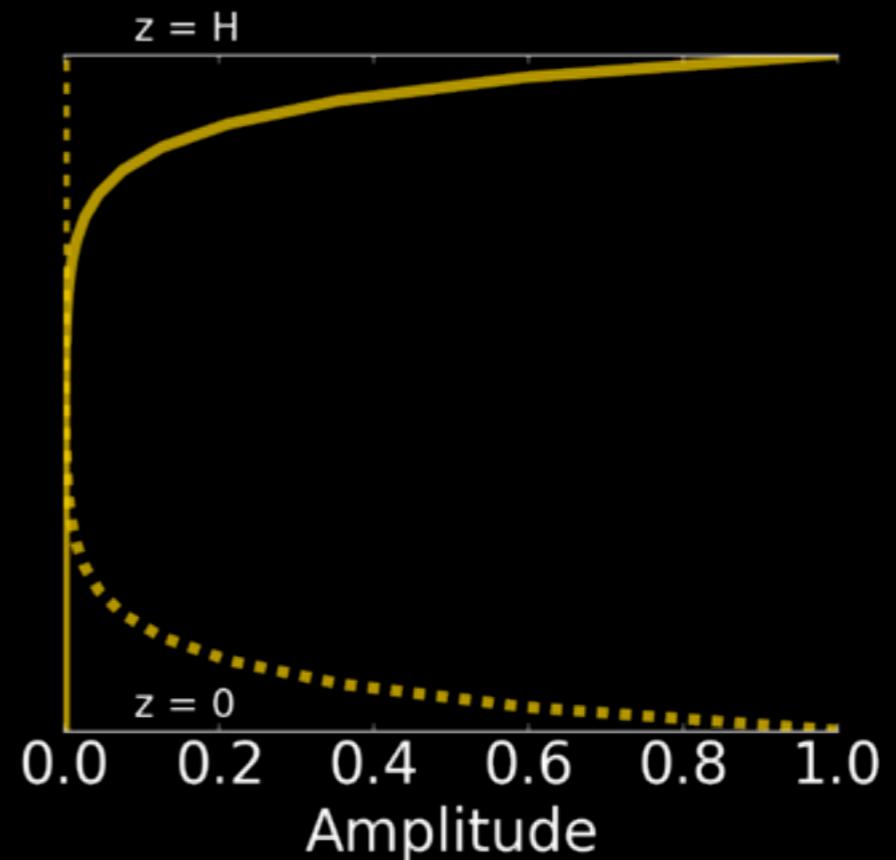
Neutral Modes

$$\lim_{\mu \rightarrow \infty} c : \quad c = 0 \quad \text{or} \quad c = \Lambda H$$

$$\varphi(z) \sim \exp\left(-\mu \frac{z}{H}\right) \quad \text{or} \quad \varphi(z) \sim \exp\left(\mu \frac{z - H}{H}\right)$$

Similar to
SQG solutions

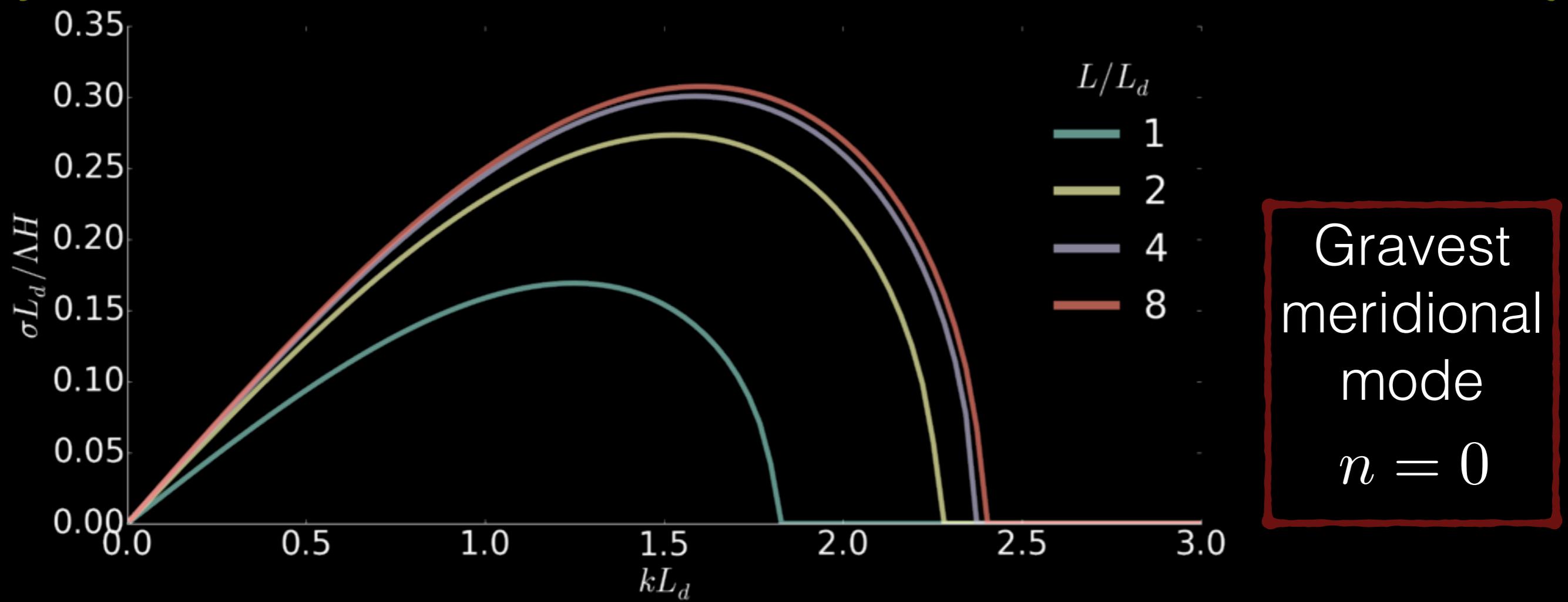
e.g. Tulloch & Smith 2006



Unstable Modes

Growth rate

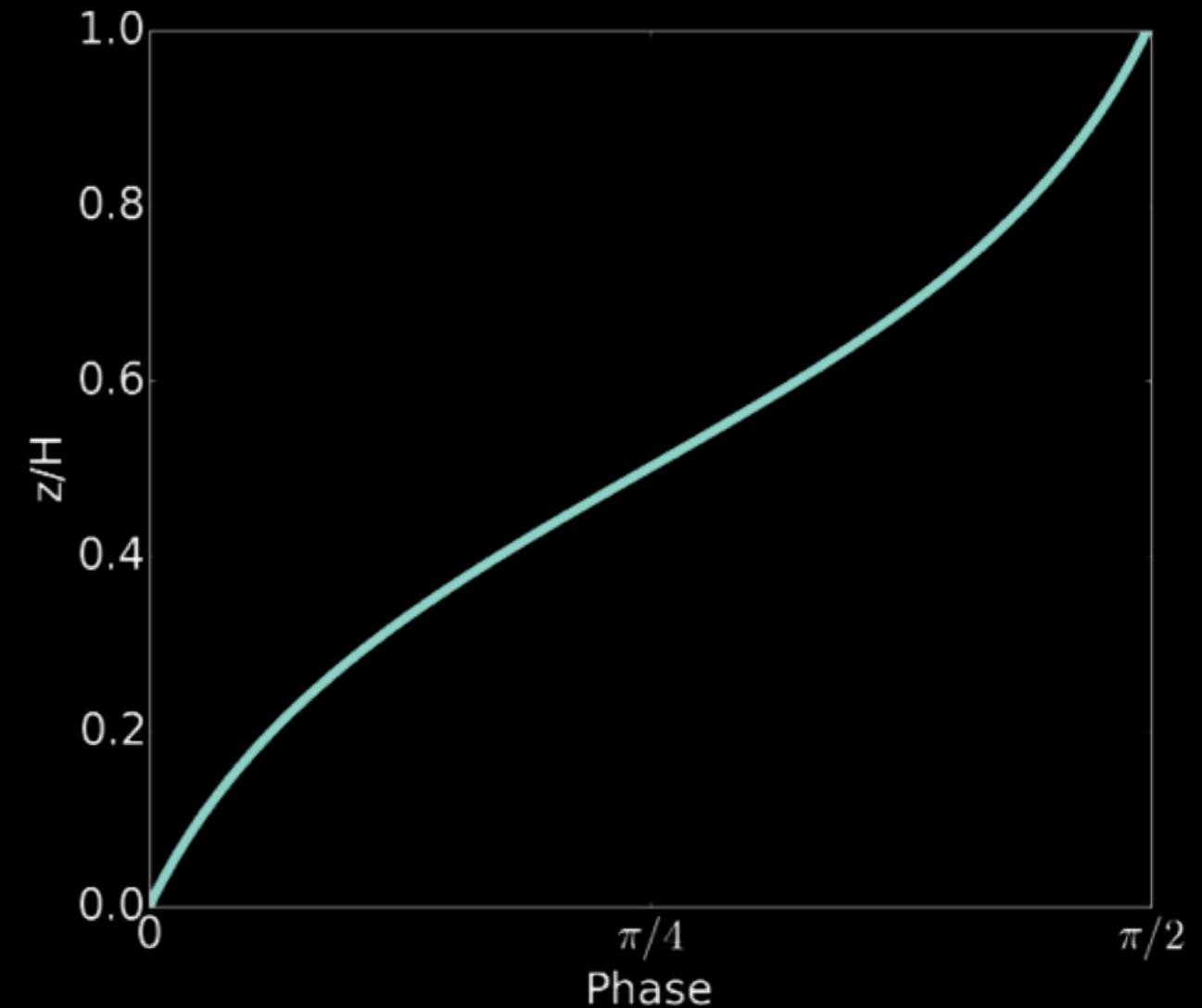
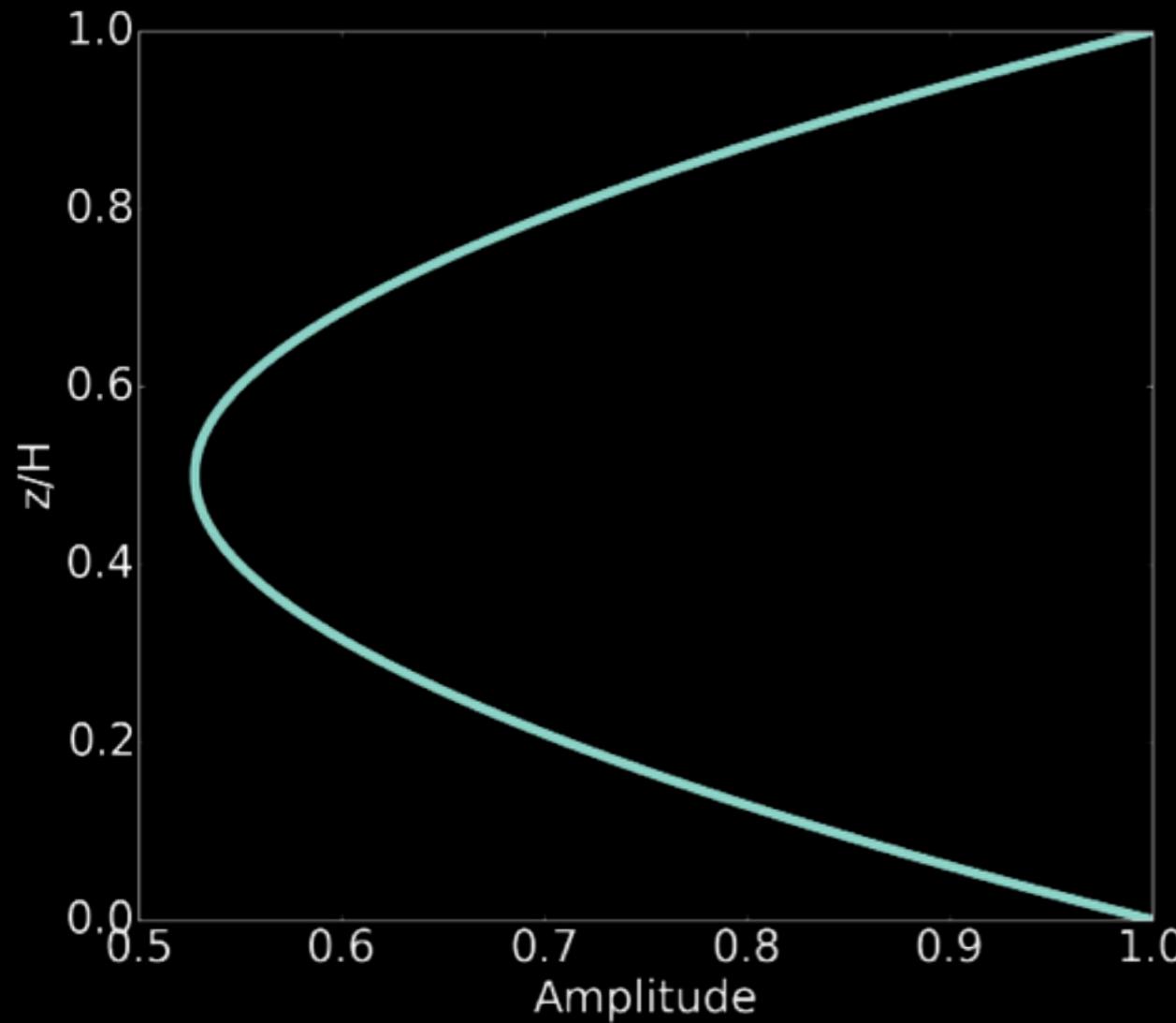
$$\sigma = kc_i = \frac{k\Lambda H}{\mu} \left\{ \left[\frac{\mu}{2} - \tanh\left(\frac{\mu}{2}\right) \right] \left[\coth\left(\frac{\mu}{2}\right) - \frac{\mu}{2} \right] \right\}^{1/2}$$



Vertical Structure

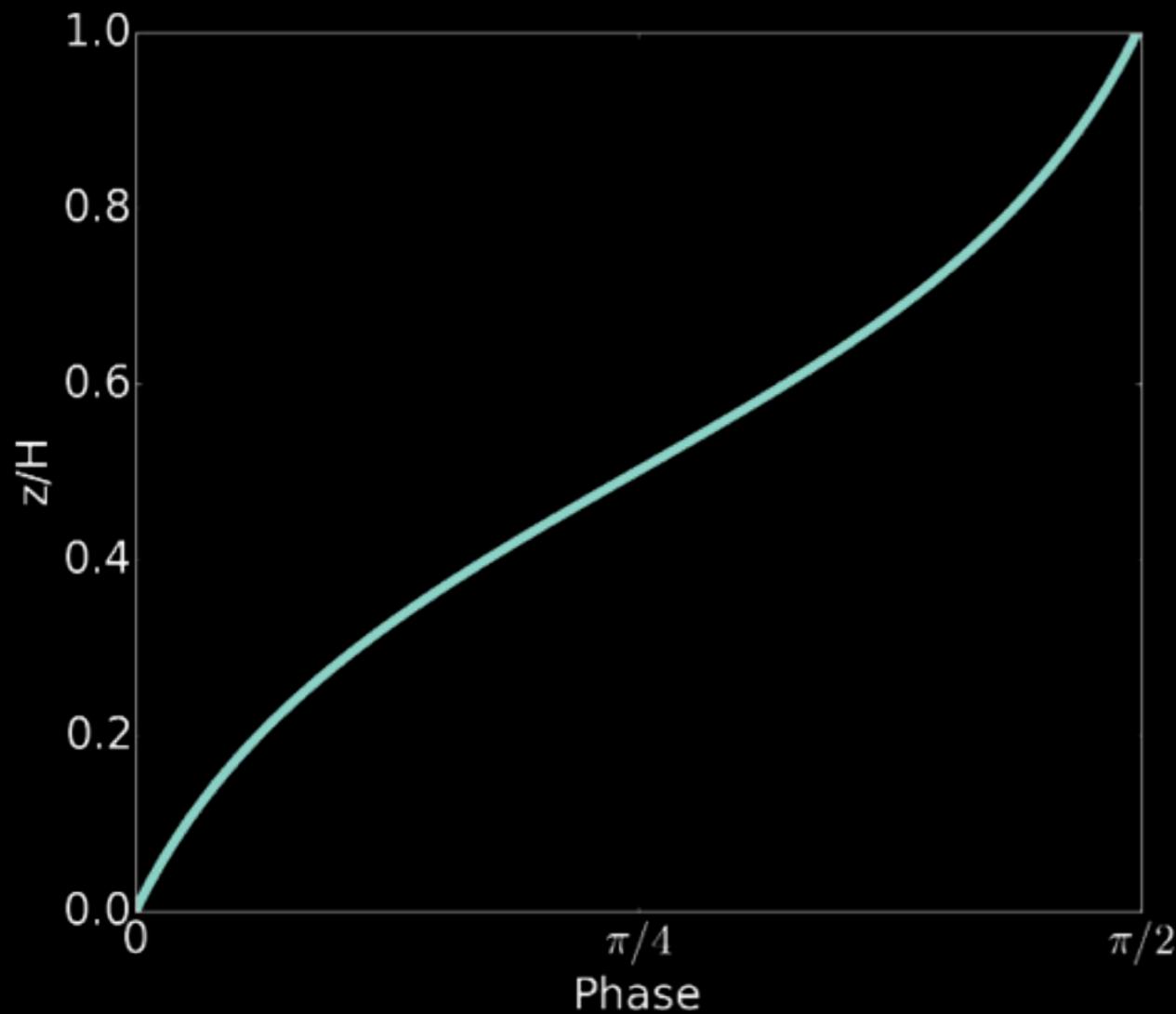
$$\varphi(z) = \cosh(\mu z) - \frac{\sinh(\mu z)}{\mu c}$$

$$n = 0 \quad L/L_d = 8$$
$$kL_d = 1.6$$



Vertical Structure

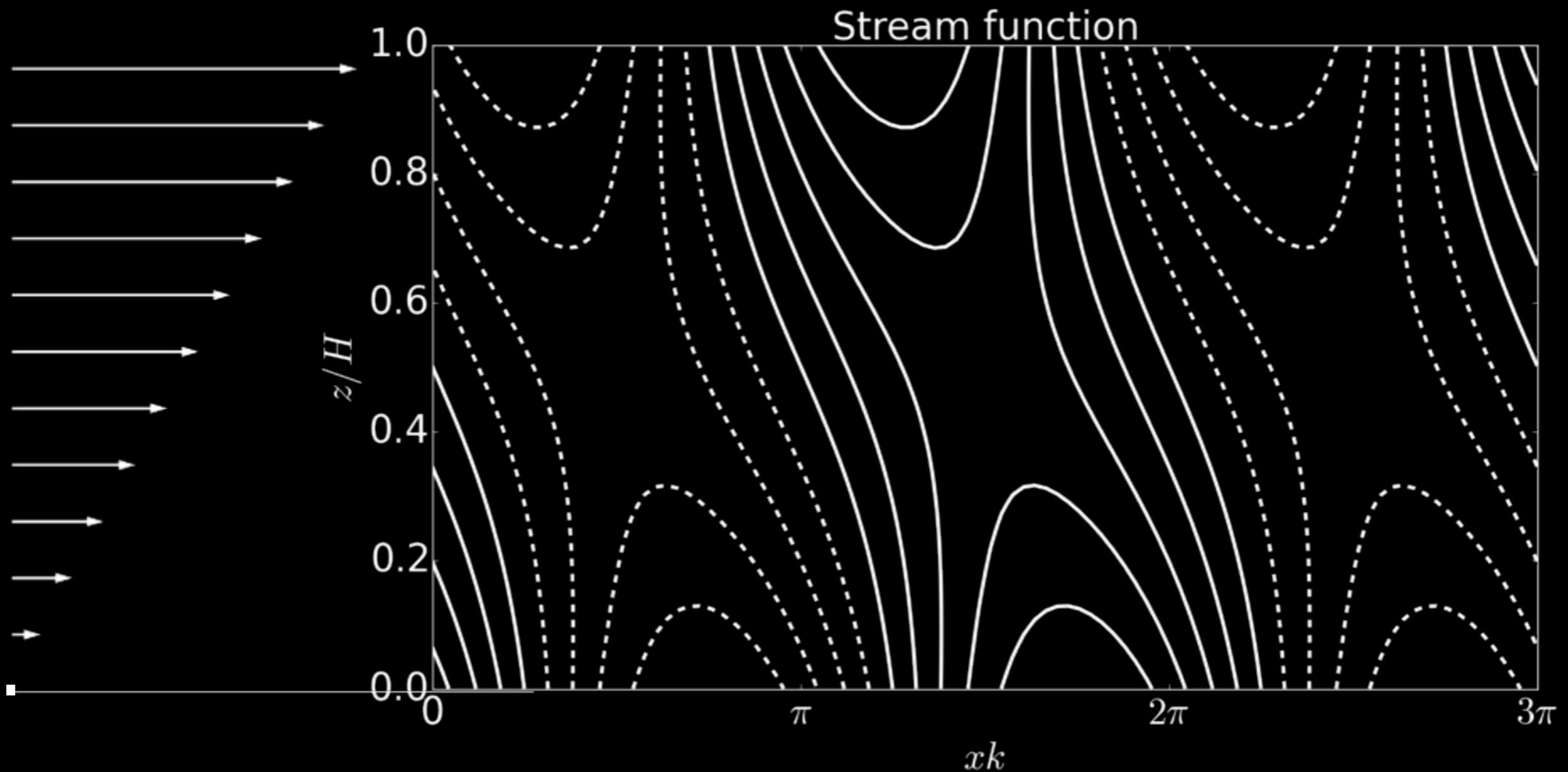
$$\psi \sim \exp i[kx + \text{Phase}(z)] \rightarrow x = -\text{Phase}(z)/k + \text{const.}$$



Perturbations lean against
the mean shear

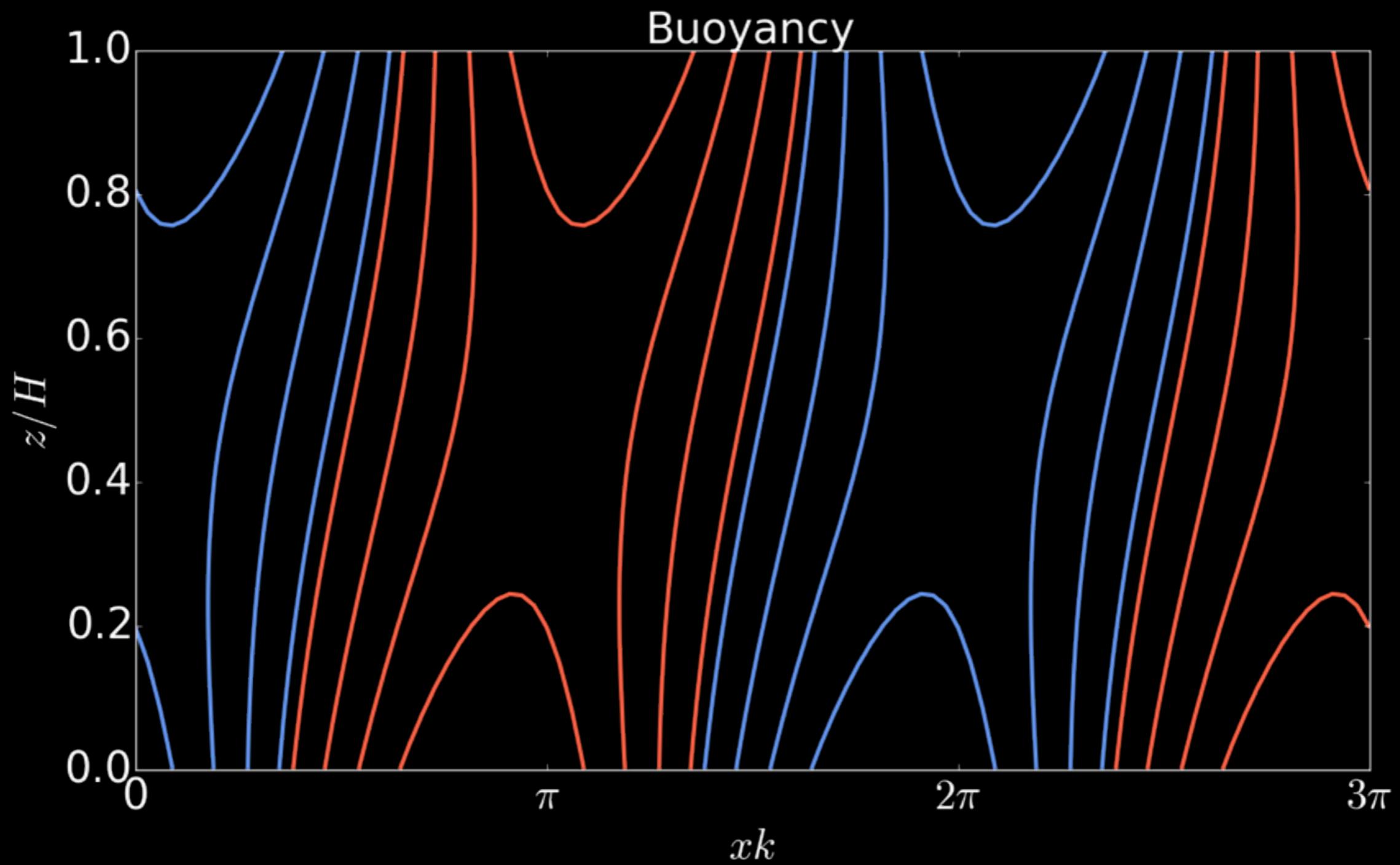
Vertical Structure

$$\psi \sim |\varphi(z)| \cos[kx + \text{Phase}(z) + \text{const.}]$$



Vertical Structure

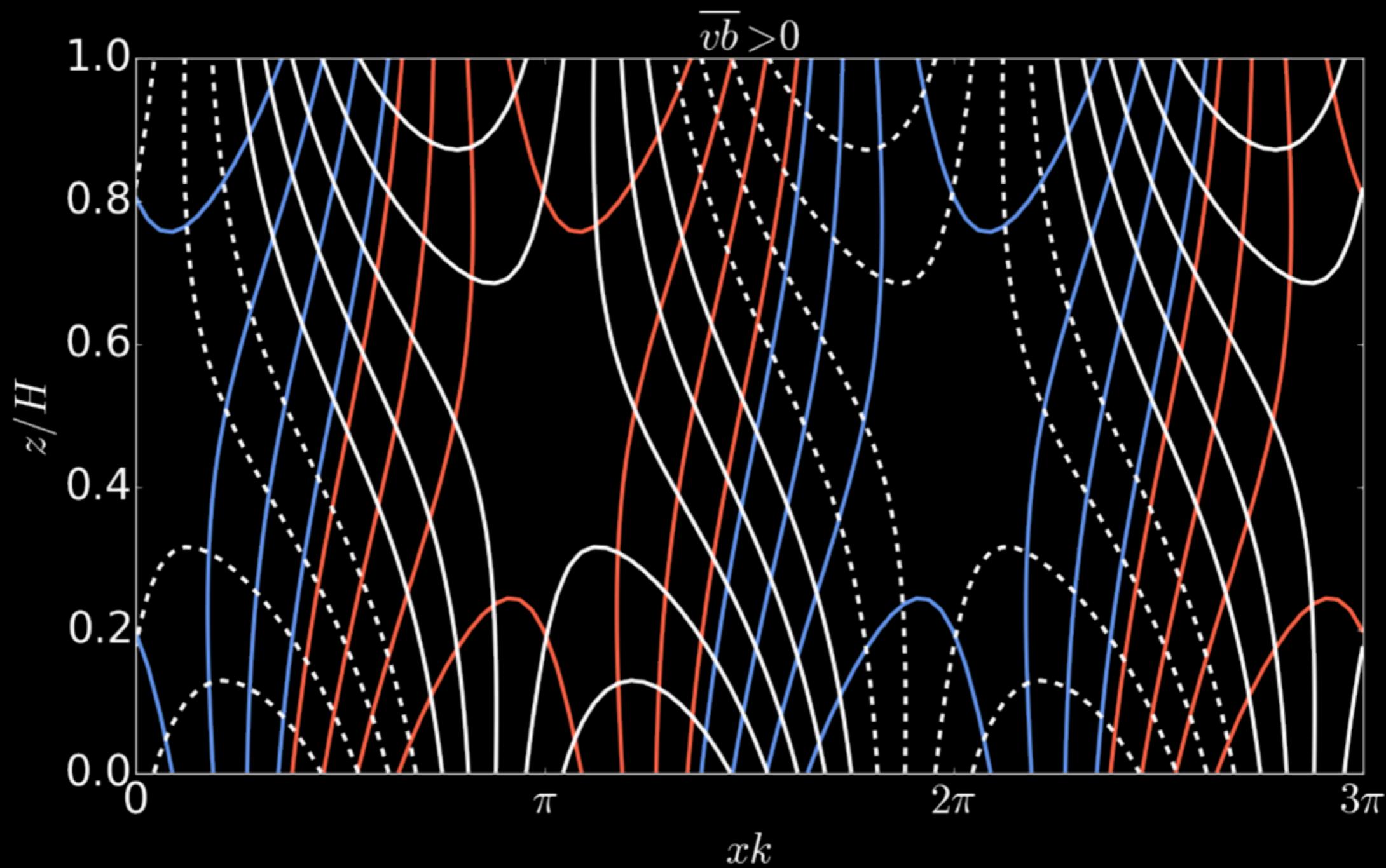
$$b \sim \psi_z$$



Buoyancy Fluxes

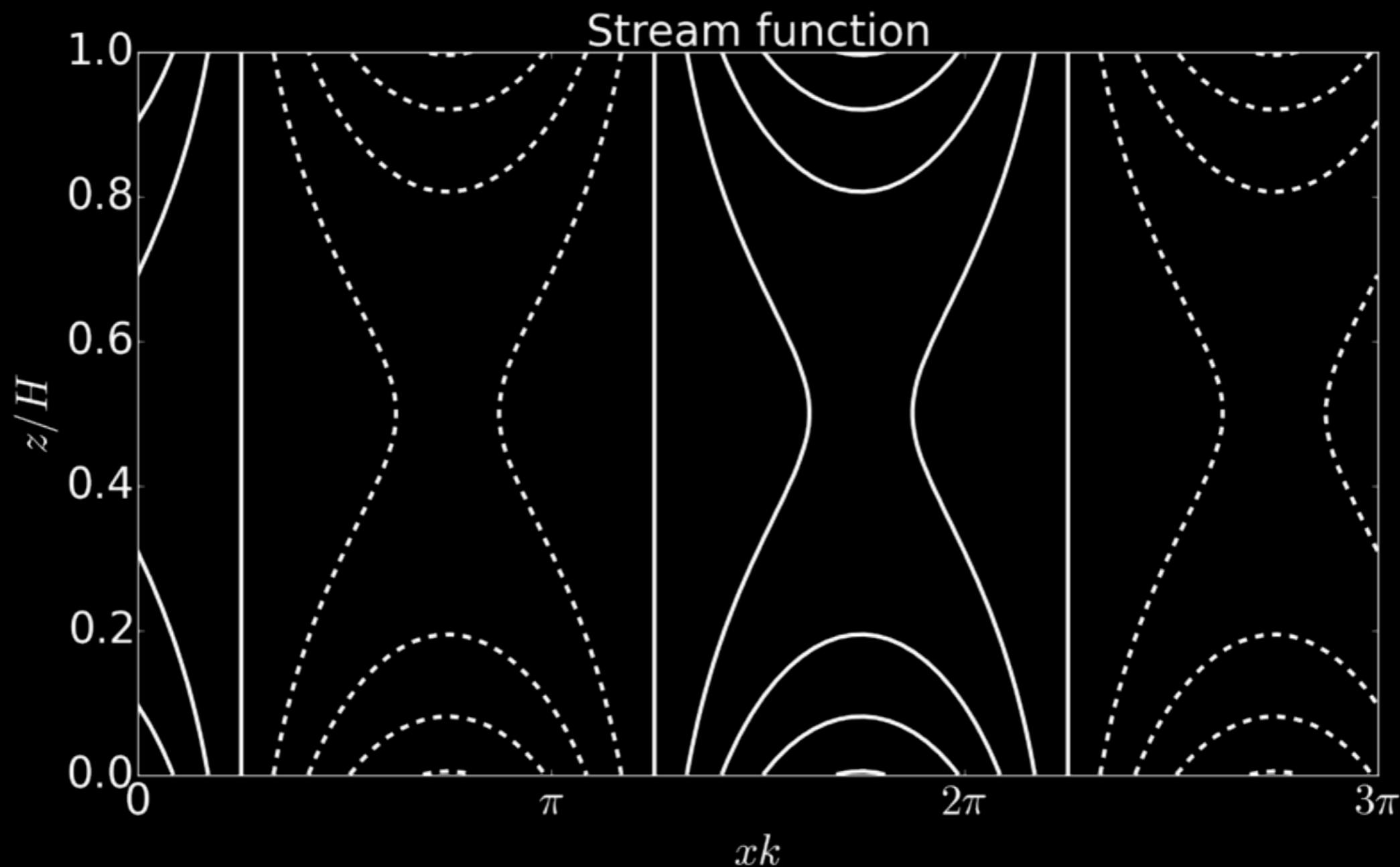
$$\bar{vb} \sim |\varphi(z)|^2 [\text{Phase}(z)]_{z>0}$$

Poleward flux

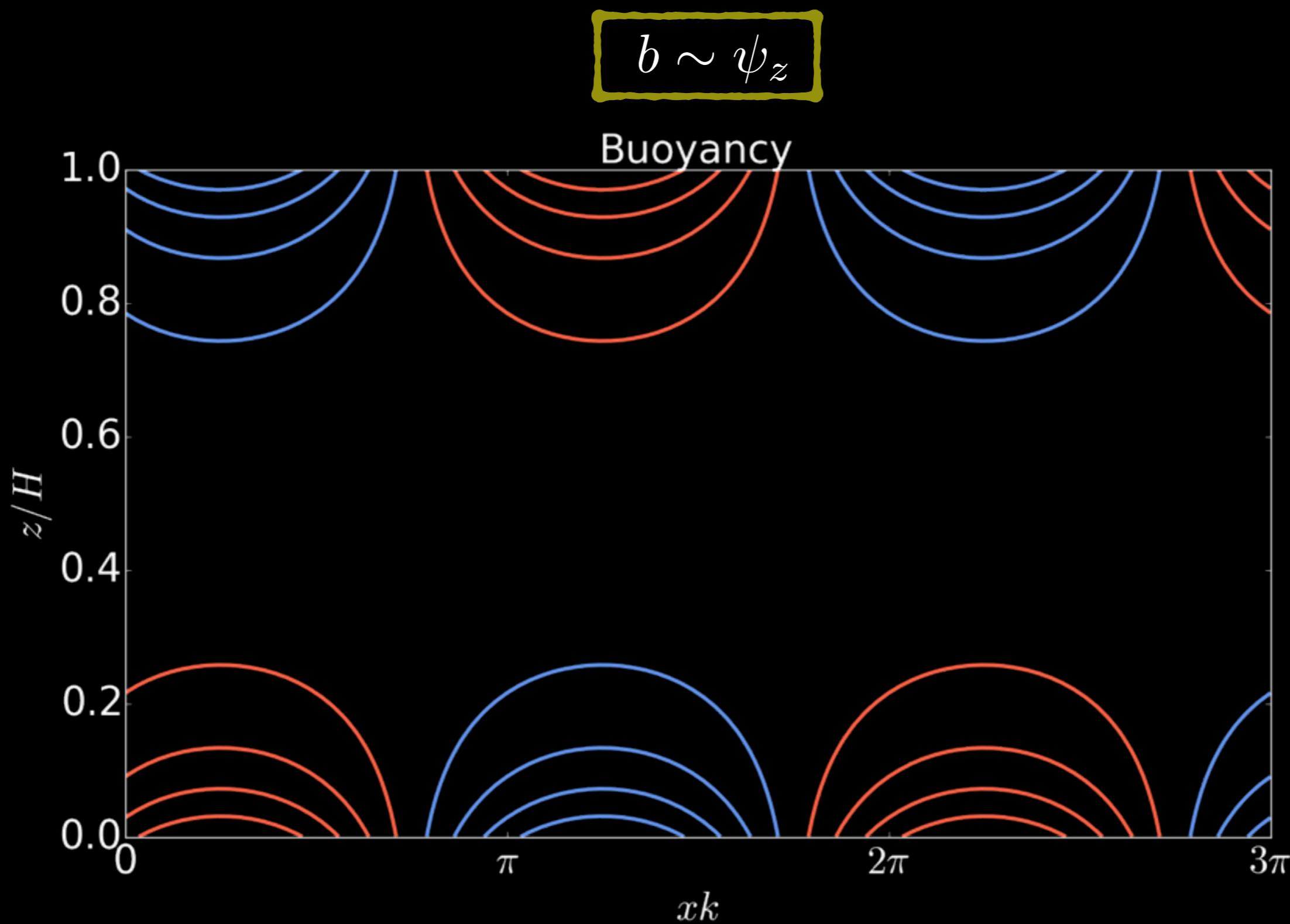


Neutral Modes

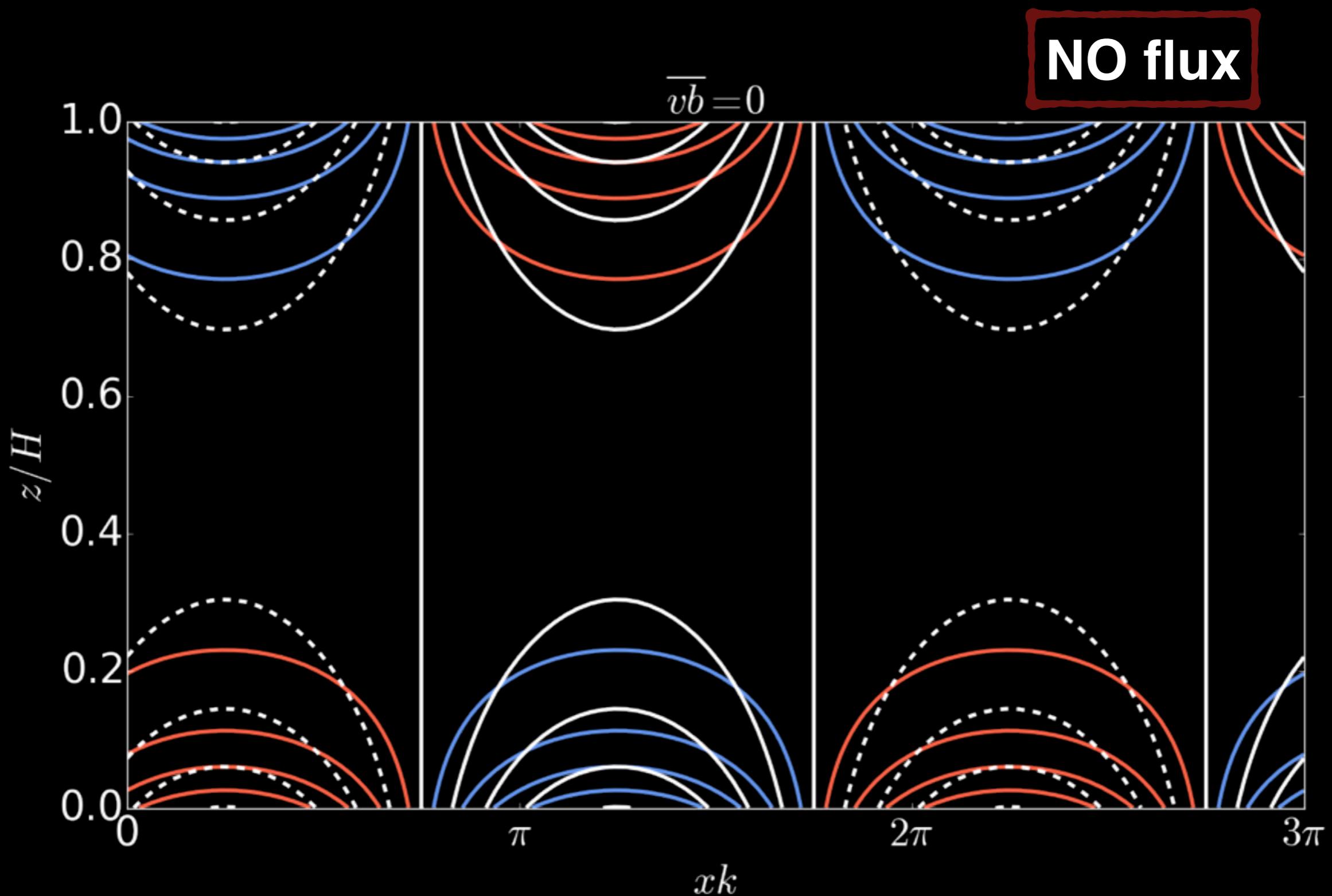
$$\psi \sim \varphi(z) \cos(kx + \text{const.})$$



Neutral Modes



Neutral Modes



Some Numbers

$$L_{max} = \frac{2\pi}{k_{max}} \approx 3.9L_d$$

$$\sigma_{max} \approx 0.3 \frac{U}{L_d}$$

Atmosphere

L_{max} 4000 km

σ_{max} 0.26 day^{-1}

T 4 days

Ocean

400 km

0.026 day^{-1}

40 days

A note on adding β

- Vallis 2006: Numerical solutions
- Lindzen 1994:
$$\left[\frac{f_0^2}{N^2(z)} U_z \right]_z = \beta \quad (Q_y = 0)$$

Differential rotation introduces a low wavenumber cutoff
(Similar to two-layer model)

Similarity to Interior Inst.

PV sheets

(Bretherton 1966)

$$Q_{upper} = -\frac{f_0^2}{N^2(z)} \frac{\partial \psi}{\partial z} \delta(z - H + \epsilon)$$

$$Q_{lower} = \frac{f_0^2}{N^2(z)} \frac{\partial \psi}{\partial z} \delta(z - \epsilon)$$

$$\int_0^H Q_y dz = \frac{f_0^2}{N^2(z)} \frac{\partial U}{\partial z} \Big|_{z=H-\epsilon} - \frac{f_0^2}{N^2(z)} \frac{\partial U}{\partial z} \Big|_{z=\epsilon}$$